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Directed strongly regular graphs from $1\frac{1}{2}$ -designs

A.E. Brouwer^a, O. Olmez^b, S.Y. Song^{b,1}^a Department of Mathematics, Technological University Eindhoven, P.O. Box 513, 5600 MB Eindhoven, The Netherlands^b Department of Mathematics, Iowa State University, Ames, IA, 50011, USA

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ABSTRACT

Some families of directed strongly regular graphs with $t = \mu$ are constructed by using antiflags of $1\frac{1}{2}$ -designs.

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1. Introduction

A *finite incidence structure* consists of a finite set P of *points*, a set \mathcal{B} of *blocks*, and an *incidence relation* \in between points and blocks. An incident point–block pair is called a *flag*, and a non-incident point–block pair is called an *antiflag*. A *tactical configuration with parameters* $(\mathbf{v}, \mathbf{b}, \mathbf{k}, \mathbf{r})$ is a finite incidence structure $\mathcal{T} = (P, \mathcal{B}, \in)$ with $|P| = \mathbf{v}$, $|\mathcal{B}| = \mathbf{b}$ such that every block contains \mathbf{k} points and every point belongs to exactly \mathbf{r} blocks.

A $1\frac{1}{2}$ -*design* [6] or *partial geometric design* [1] with parameters $(\mathbf{v}, \mathbf{b}, \mathbf{k}, \mathbf{r}; a, b)$ is a tactical configuration $\mathcal{T} = (P, \mathcal{B}, \in)$ with parameters $(\mathbf{v}, \mathbf{b}, \mathbf{k}, \mathbf{r})$ satisfying the following property.

For every point $x \in P$ and every block $B \in \mathcal{B}$, the number of flags (y, C) such that $y \in B$ and $C \ni x$ is a if $x \notin B$ and b if $x \in B$.

Examples of $1\frac{1}{2}$ -designs include 2-designs, complete bipartite graphs $K_{n,n}$, transversal designs, and partial geometries. The dual of a $1\frac{1}{2}$ -design is again a $1\frac{1}{2}$ -design (see [6]).

A *directed strongly regular graph* [4] with parameters (v, k, t, λ, μ) is a directed graph Γ on v vertices without loops such that (i) every vertex has in-degree and out-degree k , (ii) every vertex x has t out-neighbors that are also in-neighbors of x , and (iii) the number of directed paths of length 2 from a vertex x to another vertex y is λ if there is an edge from x to y , and is μ if there is no edge from x to y . Such a graph Γ is called a $\text{DSRG}(v, k, t, \lambda, \mu)$.

E-mail addresses: aeb@cwi.nl (A.E. Brouwer), oolmez@iastate.edu (O. Olmez), sysong@iastate.edu (S.Y. Song).

¹ Tel.: +1 515 294 5866; fax: +1 515 294 5454.

Let I denote the identity matrix, and J the all-1 matrix (not necessarily square), with sizes that are clear from the context. The adjacency matrix of a directed strongly regular graph is a square $(0, 1)$ -matrix A with zero diagonal such that the \mathbb{Z} -linear span of I, J , and A is closed under matrix multiplication. Equivalently, it is a square $(0, 1)$ -matrix A with zero diagonal such that for certain constants k, t, λ, μ we have $AJ = JA = kJ$ and $A^2 = tI + \lambda A + \mu(J - I - A)$.

The incidence matrix of a $1\frac{1}{2}$ -design is a $(0, 1)$ -matrix N such that for certain constants $\mathbf{k}, \mathbf{r}, a, b$ we have $JN = \mathbf{k}J$, $NJ = \mathbf{r}J$, and $NN^T N = (b - a)N + aJ$.

In this note, we observe the following. Given a $1\frac{1}{2}$ -design with incidence matrix N , define a matrix A , with rows and columns indexed by the point-block pairs (p, B) for which $N_{pB} = 0$, by $A_{(p,B), (q,C)} = N_{pC}$. Then A is a directed strongly regular graph. This yields directed strongly regular graphs with previously unknown parameters (see [2,3]).

2. Construction

We show that the set of antiflags of a $1\frac{1}{2}$ -design gives rise to a directed strongly regular graph with parameters $t = \mu$.

Theorem 2.1. *Let $\mathcal{T} = (P, \mathcal{B}, \in)$ be a tactical configuration with parameters $(\mathbf{v}, \mathbf{b}, \mathbf{k}, \mathbf{r})$. Let $\Gamma = \Gamma(\mathcal{T})$ be the directed graph defined by*

$$V(\Gamma) = \{(p, B) \in P \times \mathcal{B} : p \notin B\}$$

and

$$(p, B) \rightarrow (q, C) \quad \text{if and only if} \quad p \in C.$$

Then Γ is directed strongly regular if and only if \mathcal{T} is a $1\frac{1}{2}$ -design.

Proof. Let Γ have adjacency matrix A . Write pB for an antiflag (p, B) . Then

$$(A^2)_{pB, qC} = \sum_{rD} A_{pB, rD} A_{rD, qC} = \sum_{rD} N_{pD} N_{rC} (1 - N_{rD}) = \mathbf{k}\mathbf{r} - (NN^T N)_{pC}.$$

If \mathcal{T} is a $1\frac{1}{2}$ -design with parameters $(\mathbf{v}, \mathbf{b}, \mathbf{k}, \mathbf{r}; a, b)$, then $NN^T N = (b - a)N + aJ$, and hence $A^2 = (\mathbf{k}\mathbf{r} - a)J - (b - a)A$, so Γ is a directed strongly regular graph with parameters

$$v = \mathbf{b}(\mathbf{v} - \mathbf{k}), \quad k = \mathbf{r}(\mathbf{v} - \mathbf{k}), \quad t = \mu = \mathbf{k}\mathbf{r} - a, \quad \lambda = \mathbf{k}\mathbf{r} - b.$$

Conversely, suppose that Γ is a DSRG(v, k, t, λ, μ). Then $A^2 = (t - \mu)I + (\lambda - \mu)A + \mu J$, and we find that $\mathbf{k}\mathbf{r} - (NN^T N)_{pC} = (t - \mu)\delta_{pB, qC} + (\lambda - \mu)N_{pC} + \mu$ for all antiflags pB, qC (where $\delta_{pB, qC}$ is 1 when $pB = qC$ and 0 otherwise). If $t \neq \mu$ then $\delta_{pB, qC}$ is determined by p, C and is independent of q, B . This can hold only for $\mathbf{v} = \mathbf{k} + 1$, $\mathbf{b} = \mathbf{r} + 1$, and $A = J - I$, so μ is undefined. Therefore, we may assume that $t = \mu$, so $NN^T N = (\mu - \lambda)N + (\mathbf{k}\mathbf{r} - \mu)J$. \square

Similarly, the set of flags of a $1\frac{1}{2}$ -design gives a directed strongly regular graph with $t = \lambda + 1$.

Theorem 2.2. *Let $\mathcal{T} = (P, \mathcal{B}, \in)$ be a tactical configuration with parameters $(\mathbf{v}, \mathbf{b}, \mathbf{k}, \mathbf{r})$. Let Γ be the directed graph defined by*

$$V(\Gamma) = \{(p, B) \in P \times \mathcal{B} : p \in B\}$$

and

$$(p, B) \rightarrow (q, C) \quad \text{if and only if} \quad (p, B) \neq (q, C) \text{ and } p \in C.$$

Then Γ is directed strongly regular if and only if \mathcal{T} is a $1\frac{1}{2}$ -design.

Proof. This time, write pB for a flag (p, B) . Let Γ have adjacency matrix A , and put $M = A + I$ so that $M_{pB, qC} = N_{pC}$. Then

$$(M^2)_{pB, qC} = \sum_{rD} M_{pB, rD} M_{rD, qC} = \sum_{r, D} N_{pD} N_{rC} N_{rD} = (NN^T N)_{pC}.$$

If \mathcal{T} is a $1\frac{1}{2}$ -design with parameters $(\mathbf{v}, \mathbf{b}, \mathbf{k}, \mathbf{r}; a, b)$, then $NN^T N = (b - a)N + aJ$, and $M^2 = (b - a)M + aJ$, so $A^2 = (M - I)^2 = (b - a - 2)A + (b - a - 1)I + aJ$, and it follows that Γ is a directed strongly regular graph with parameters

$$v = \mathbf{vr}, \quad k = \mathbf{rk} - 1, \quad t = b - 1, \quad \lambda = b - 2, \quad \mu = a.$$

Conversely, suppose that Γ is a DSRG(v, k, t, λ, μ). Then $A^2 = (t - \mu)I + (\lambda - \mu)A + \mu J$, so $M^2 = (\lambda - \mu + 2)M + \mu J + (t - \lambda - 1)I$, and therefore $(NN^T N)_{pC} = (\lambda - \mu + 2)N_{pC} + \mu + (t - \lambda - 1)\delta_{pB, qC}$. If $t \neq \lambda + 1$, then $\delta_{pB, qC}$ is determined by p, C and is independent of q, B . This can hold only for $\mathbf{k} \leq 1, \mathbf{r} \leq 1$, and λ is undefined. Therefore, we may assume that $t = \lambda + 1$, so $NN^T N = (\lambda - \mu + 2)N + \mu J$. \square

3. Examples

In this section, we give some concrete examples of new directed strongly regular graphs that are constructed by Theorem 2.1.

Example 3.1. Let P be the set of $2n$ vertices, and let \mathcal{B} be the set of n^2 edges of the complete bipartite graph $K_{n,n}$. Then the incidence structure $\mathcal{T} = (P, \mathcal{B}, \in)$ is a $1\frac{1}{2}$ -design with parameters

$$\mathbf{v} = 2n, \quad \mathbf{b} = n^2, \quad \mathbf{k} = 2, \quad \mathbf{r} = n; \quad a = 1, \quad b = n + 1.$$

Therefore the graph $\Gamma(\mathcal{T})$ is a directed strongly regular graph with parameters

$$v = 2n^2(n - 1), \quad k = 2n(n - 1), \quad t = \mu = 2n - 1, \quad \lambda = n - 1.$$

For $n = 3, 4$ we obtain directed strongly regular graphs with new parameter sets $(36, 12, 5, 2, 5)$ and $(96, 24, 7, 3, 7)$. By Duval [4], if there exists a DSRG(v, k, t, λ, μ) with $t = \mu$, then there also are DSRG($mv, mk, mt, m\lambda, m\mu$) for all positive integers m . In particular, we also find directed strongly regular graphs with parameter sets $(72, 24, 10, 4, 10)$ and $(108, 36, 15, 6, 15)$.

Example 3.2. A partial geometry $pg(\kappa, \rho, \tau)$ is a set of points P , a set of lines \mathcal{L} , and an incidence relation between P and \mathcal{L} with the following properties.

- (1) Every line is incident with κ points ($\kappa \geq 2$), and every point is incident with ρ lines ($\rho \geq 2$).
- (2) Any two points are incident with at most one line.
- (3) If a point p and a line L are not incident, then there exist exactly τ ($\tau \geq 1$) lines that are incident with p and meet L .

A partial geometry $pg(\kappa, \rho, \tau)$ is a $1\frac{1}{2}$ -design \mathcal{T} with parameters

$$(\mathbf{v}, \mathbf{b}, \mathbf{k}, \mathbf{r}; a, b) = (\kappa c, \rho c, \kappa, \rho; \tau, \mathbf{r} + \mathbf{k} - 1),$$

where $c = 1 + (\kappa - 1)(\rho - 1)/\tau$.

For example, the partial geometry obtained from an affine plane of order q by considering all q^2 points and taking the lines of l parallel classes is a $pg(q, l, l - 1)$ and hence yields a $1\frac{1}{2}$ -design \mathcal{T} with parameters $(\mathbf{v}, \mathbf{b}, \mathbf{k}, \mathbf{r}; a, b) = (q^2, ql, q, l; l - 1, q + l - 1)$ and a directed strongly regular graph $\Gamma(\mathcal{T})$ defined as in Theorem 2.1 with parameters

$$(v, k, t, \lambda, \mu) = (lq^2(q - 1), lq(q - 1), lq - l + 1, (l - 1)(q - 1), lq - l + 1).$$

For example, for $q = l = 3$, we find the previously unknown graph with parameter set $(54, 18, 7, 4, 7)$. Doubling yields the graph with parameter set $(108, 36, 14, 8, 14)$.

Remark 3.3. The above characterization theorems may be used to show non-existence of $1\frac{1}{2}$ -designs with given parameter sets. We give one example. Suppose that there exists a $1\frac{1}{2}$ -design with parameters $(8, 16, 5, 10; 25, 35)$. Then there is a directed strongly regular graph with parameters $(48, 30, 25, 15, 25)$ according to [Theorem 2.1](#). However, it is known that there is no DSRG $(48m, 30m, 25m, 15m, 25m)$ for any positive integer m by Jørgensen [5]. So, although the parameter set $(\mathbf{v}, \mathbf{b}, \mathbf{k}, \mathbf{r}; a, b) = (8, 16, 5, 10; 25, 35)$ satisfies all the necessary conditions imposed in Section 3.3 of [6], there is no $1\frac{1}{2}$ -design with these parameters.

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